BDE-RFM208P-S1 USER GUIDE

Introduction

This user guide is for BDE-RFM208P-S1, a Wireless Module based on TI CC1352P. It is a quick start guide for how to connect the module with the evaluation board BDE-EVB07 or with the TI launchpad, and how to build the first application. It also shows a demo for how BDE-RFM208P-S1 receives a data packet that is sent from another BDE-RFM208P-S1.

Get Ready

The following tools are recommended to develop with BDE-RFM208P-S1.

Hardware tools:

- Two modules of BDE-RFM208P-S1(BDE-RFM208P-S1-BDE Technology Inc. (bdecomm.com))
- Two BDE-ADP208 V1.0 (adaptor board)
- PC or Laptop
- Two BDE-EVB07 (<u>BDE-EVB07-BDE Technology Inc. (bdecomm.com)</u>) or
- Two TI Launchpad (LAUNCHXL-CC26X2R1 Evaluation board | TI.com)
- USB cable for power supply and debugging

Software tools:

- Terminal software such as CCS, IAR.
- CCS download
- Software Development Kit (SDK)

Build Your First Application

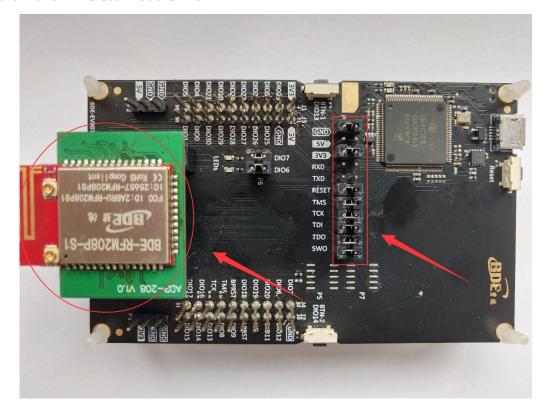
Once have the Hardware and Software tools in place, please following the following steps:

A. Connect the Hardware

If chose EVB07:

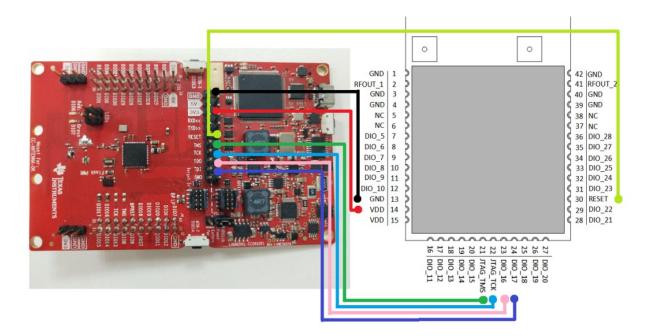
Use USB cable to connect EVB07 and PC or laptop. Plug BDE-RFM208P-S1 with the adaptor board into the dev board and connect all the pins with Jumpers as the following picture shows.

User Guide



If chose TI Launchpad:

The connection is as following.



BDE-RFM208P-S1 USER



Multi-Band Wireless Module with PA

User Guide

| Connection Designator | BDE-RFM208P-S1 LaunchPad Pin | |
|-----------------------|------------------------------|-------|
| 3V3 Power | VDD | 3V3 |
| Ground | GND | GND |
| RST | RST | RESET |
| TMS | TMS | TMS |
| TCK | TCK | TCK |
| TDO | DIO16 | TDO |
| TDI | DIO17 | TDI |

Optional: TDO, TDI, RXD, TXD

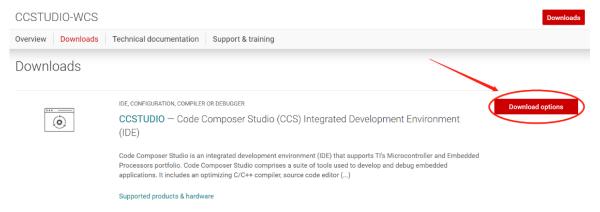
B. Build the Application

Download and install the CCS and SDK

From the above links, follow the instructions in the following steps to download and install the CCS and SDK.

CCS Installation

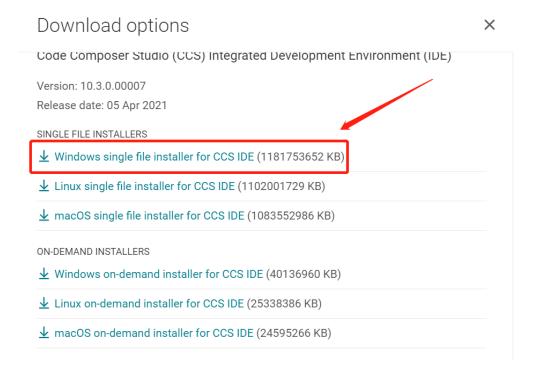
1. Click on this option



2. Select an option to download CCS

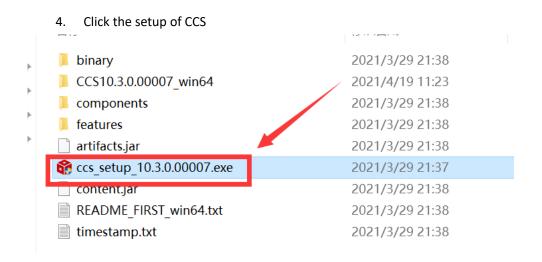


User Guide



3. Unzip the package to a local disc

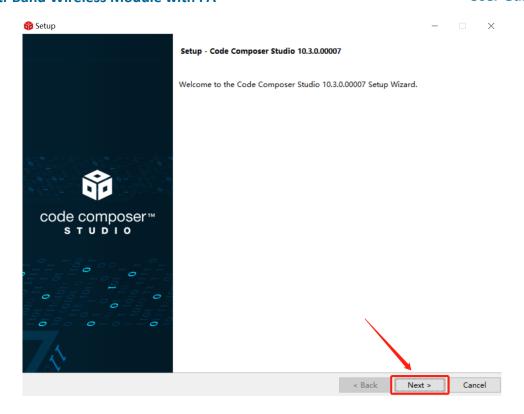




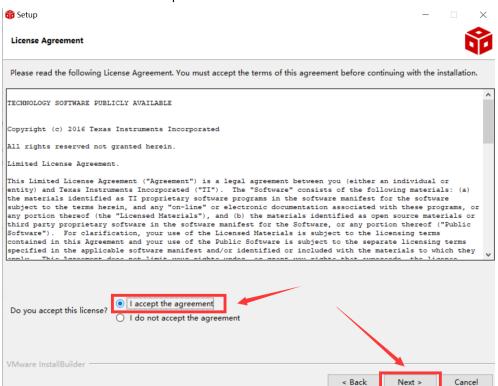
5. Click "Next"



User Guide



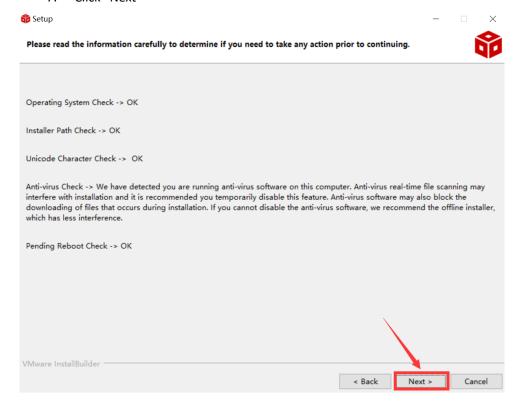
6. Select the default option



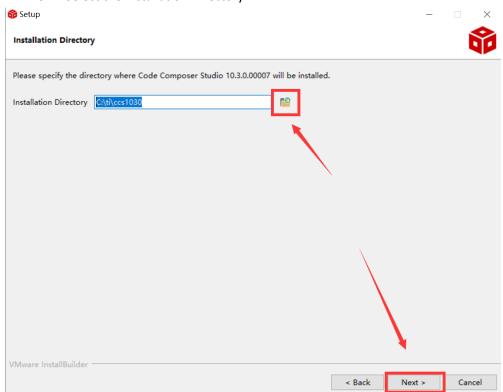


User Guide

7. Click "Next"



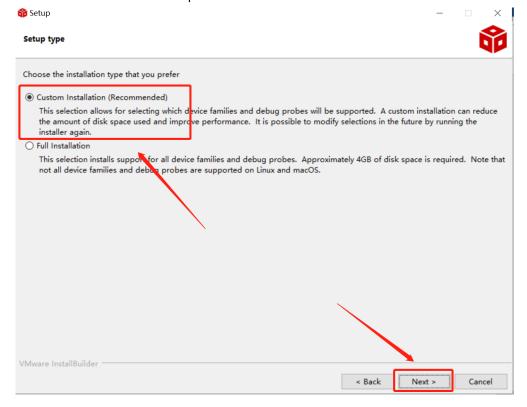
8. Select the Installation Directory



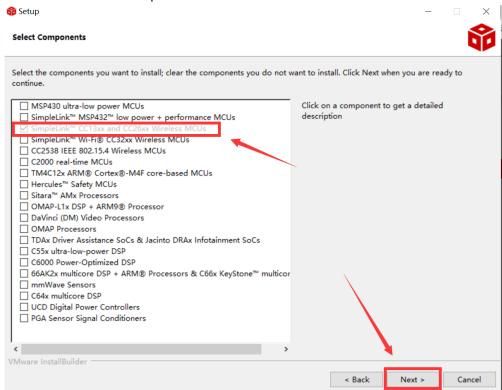


User Guide

9. Select the default option

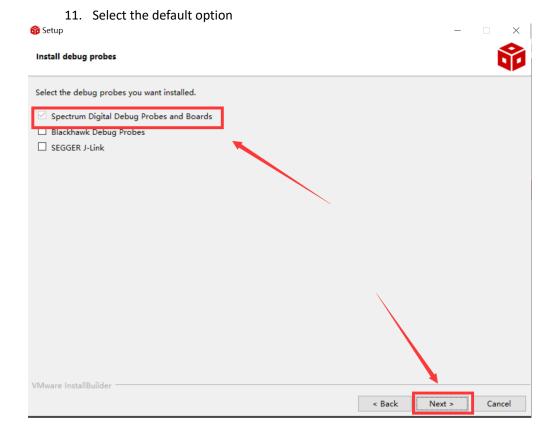


10. Select the component

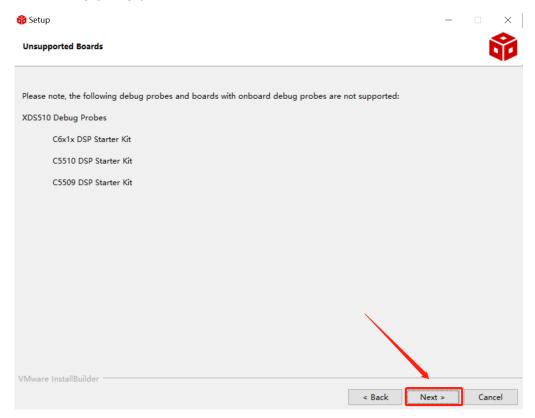




User Guide



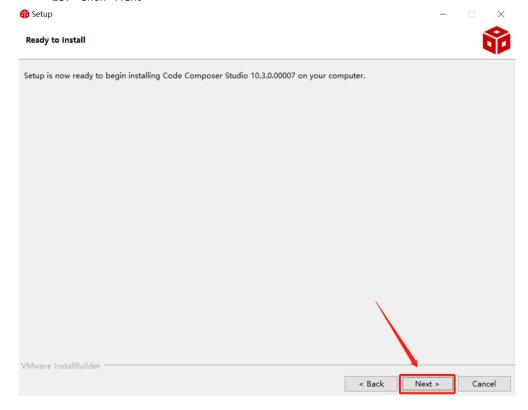
12. Click "Next"



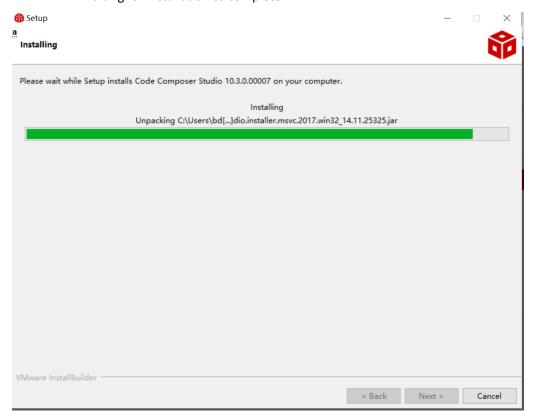


User Guide

13. Click "Next"



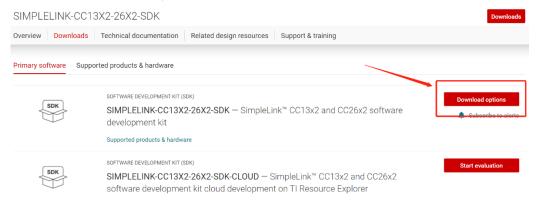
14. Waiting for installation to complete



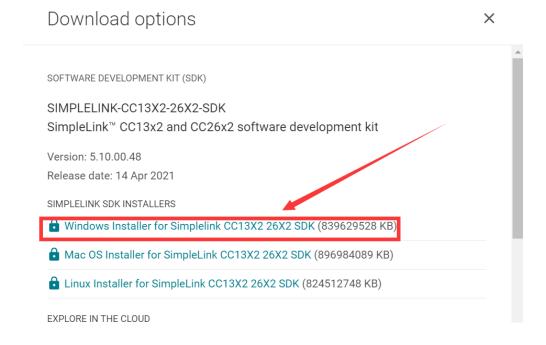


User Guide

- Software Development Kit (SDK) installation
 - 1. Click on this option



2. Select an option you need to download SDK



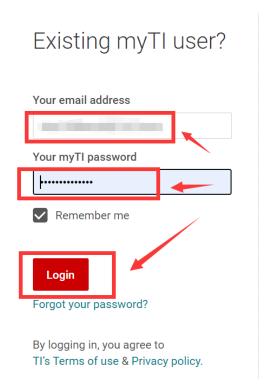
3. Log in to your TI account, if you are a new user, register a TI account first



User Guide

myTl account

myTI FAQ



4. Select "civil" if your application is for civil use





User Guide

5. Select "Yes" and submit

compliance with any such import, use, or export restrictions.

- I / We hereby certify that we will adhere to the conditions above.
- I / We do not know of any additional facts different from the above.
- I / We take responsibility to comply with these terms.
- I / We understand we are responsible to abide by the most current. versions of the Export Administration Regulations and other U.S. export and sanctions laws.



6. Download SDK

TI Home

TI Request

You have been approved to receive this file. Click "Download" to proceed.

In a few moments, you will also receive an email with the link to this file.

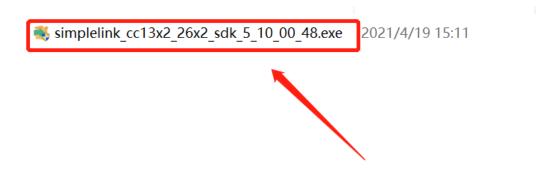


Thank you, Texas Instruments

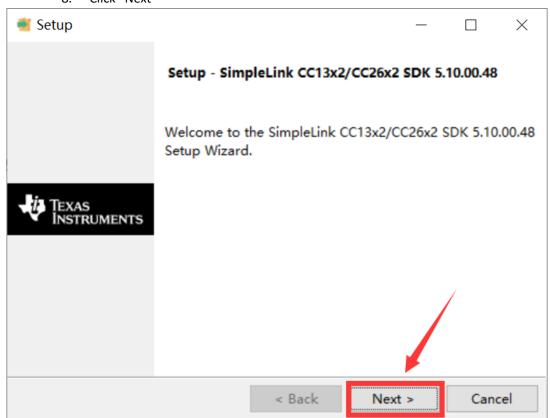
7. Installation



User Guide



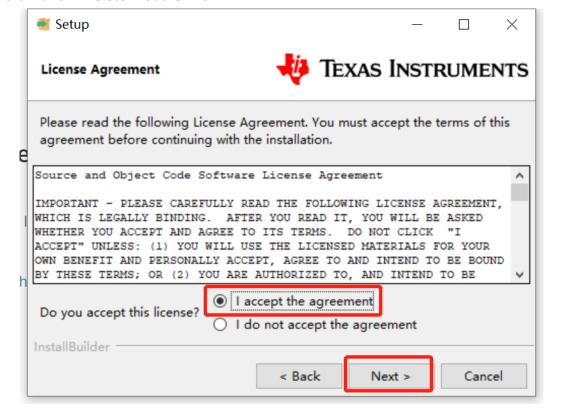
8. Click "Next"



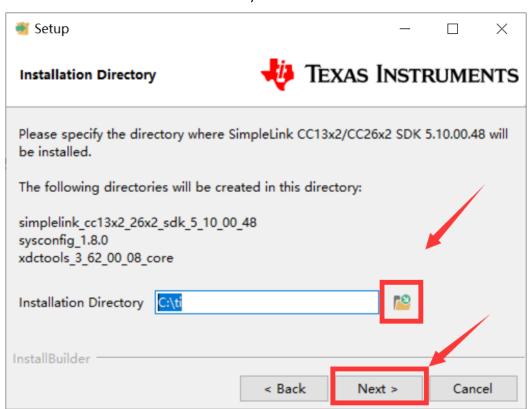
9. Select the default option



User Guide



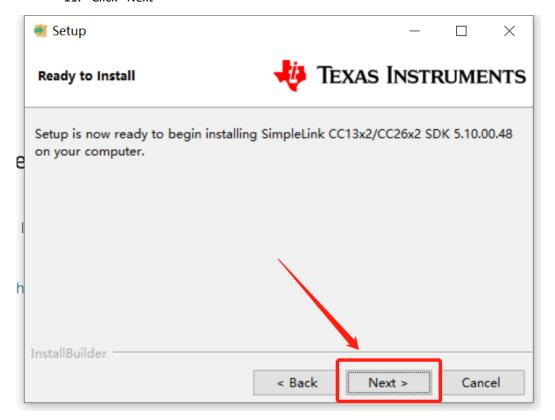
10. Select the Installation directory



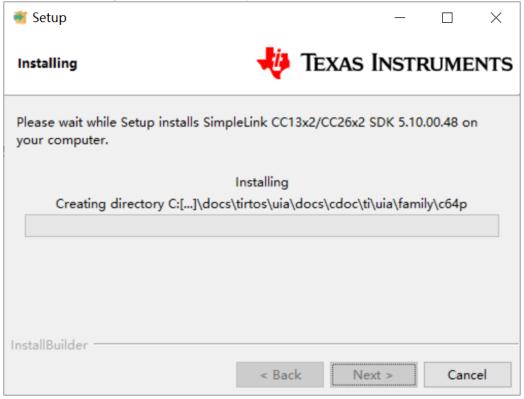


User Guide

11. Click "Next"



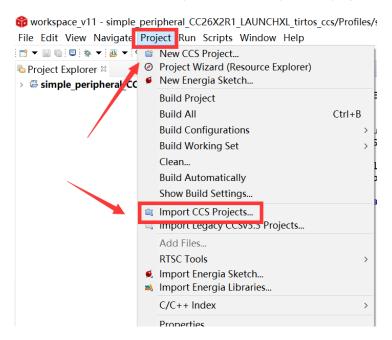
12. Waiting for installation to complete



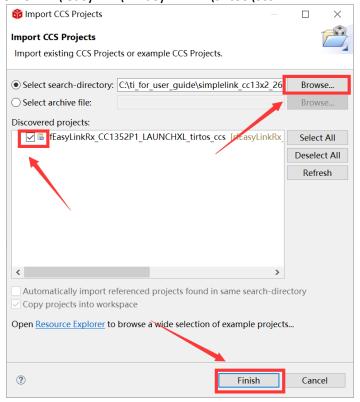


User Guide

- Run an example/demo code
 - 1. For the first module, find the option named "Import CCS project..."



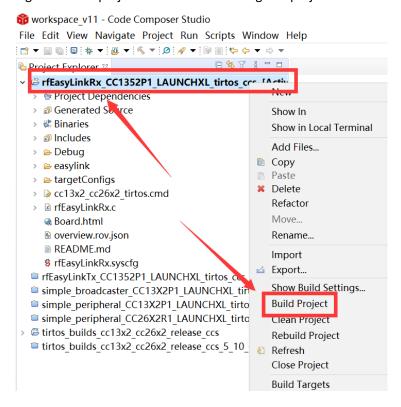
2. According to the following path to find the sending end project: ti\simplelink_cc13x2_26x2_sdk_5_10_00_48\examples\rtos\CC1352P1_L AUNCHXL\ easylink\ rfEasyLinkRx\tirtos\ccs



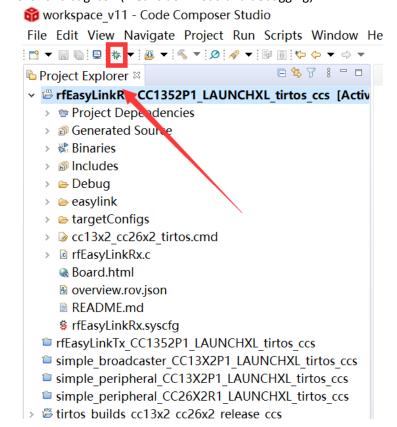


User Guide

3. Right Click the project to build the receiving end project



4. Click this bug icon (means download and debugging)





User Guide

5. Click on this option to start debugging

```
📸 workspace v11 - rfEasyLinkRx CC1352P1 LAUNCHXL tirtos ccs/rfEasyLinkRx
File Edit View Project Tools Run Scripts Window Help

♦ Debug 

□
      = main() at rft. syLinkRx.c:211 0x000036F0

☐ rfEasyLinkRx.c 
☐
 209 */
 210 int main(void)
211 {
 212
        /* Call driver init functions */
 213
        Board initGeneral();
 214
 215
        /* Open LED pins */
        ledPinHandle = PIN_open(&ledPinState, pinTable);
 216
        Assert_isTrue(ledPinHandle != NULL, NULL);
 217
 218
 219
        /* Clear LED pins */
        PIN_setOutputValue(ledPinHandle, CONFIG_PIN_GLED, 0);
 220
 221
        PIN_setOutputValue(ledPinHandle, CONFIG_PIN_RLED, 0);
 222
 223
        rxTask_init(ledPinHandle);
 224
 225
        /* Start BIOS */
```

6. Find the file which is named "rfEasyLinkRx.c" and the function which is named "rxDoneCb", and set a breakpoint at the line as the arrows shows

```
😚 workspace_v11 - rfEasyLinkRx_CC1352P1_LAUNCHXL_tirtos_ccs/rfEasyLinkRx.c - Coc
File Edit View Project Tools Run Scripts Window Help
Texas Instruments XDS110 USB Debug Probe/Cortex_M4_0 (Running)

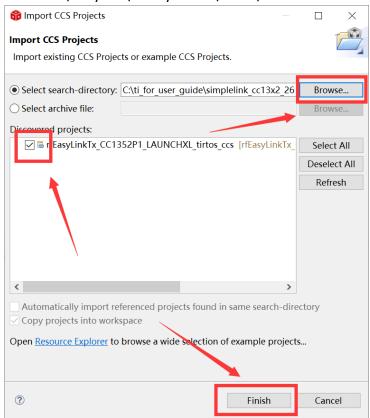
☐ rfEasyLinkRx.c 
☐

  89#ifdef RFEASYLINKRX_ASYNC
  90 static Semaphore_Handle rxDoneSem;
 91#endif
 92
 93/**** Function definitions *****/
  94#ifdef RFEASYLINKRX ASYNC
 95void rxDoneCb(EasyLink_RxPacket * rxPacket, EasyLink_Status stat
        if (status == EasyLink_Status_Success)
 97
 98
             * Toggle RLED to indicate RX */
 99
≯100
           PIN_setOutputValue(pinHandle, CONFIG_PIN_RLED,!PIN_getOu
 101
 02
        else if(status == EasyLink_Status_Aborted)
 193
        {
 104
            /* Toggle GLED to indicate command aborted */
 103
            PIN_setOutputValue(pinHandle, CONFIG_PIN_GLED,!PIN_getOu
        }
 107
        else
 108
        {
            /* Toggle GLED and DLED to indicate error */
```

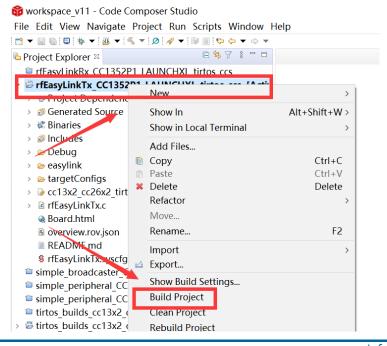


User Guide

- 7. For another module, according to the following path to find the sending end project:
 - ti\simplelink_cc13x2_26x2_sdk_5_10_00_48\examples\rtos\CC1352P1_L AUNCHXL\ easylink\ rfEasyLinkTx\tirtos\ccs



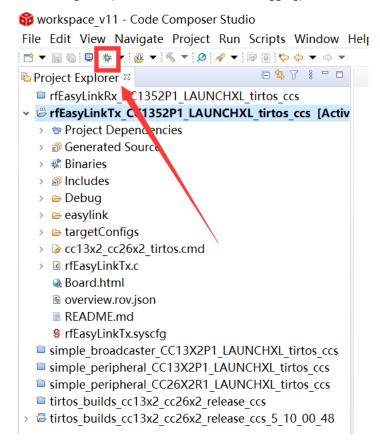
8. Right Click the project to build the sending end project





User Guide

9. Click this bug icon (means download and debugging)



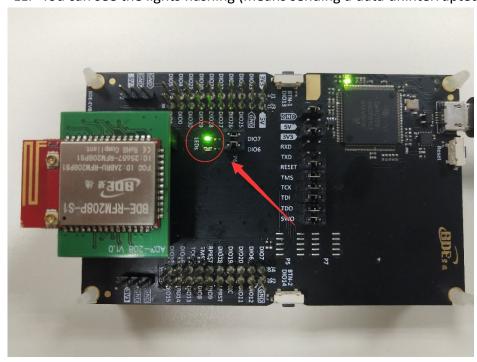
10. Click on this option to start debugging

```
😚 workspace v11 - simple peripheral CC13X2P1 LAUNCHXL tirtos ccs/Startup/main.
File Edit View Project Tools Run Scripts Window Help
= main() main.c:122 0x0000D738
<
isimple_gatt_profile
                   116
 117 * @param
                  None.
 118 *
 119 * @return
                  Nane.
 120 */
 121 int main()
 122 {
      /* Register Application callback to trap asserts raised in the
 123
 124 RegisterAssertCback(AssertHandler);
 125
 126 Board_initGeneral();
 127
 128 // Enable iCache prefetching
 129 VIMSConfigure(VIMS_BASE, TRUE, TRUE);
 130
     // Enable cache
     VIMSModeSet(VIMS BASE, VIMS MODE ENABLED);
 131
 132
 133 #if !defined( POWER SAVING )
 134 /* Set constraints for Standby, powerdown and idle mode */
```



User Guide

11. You can see the lights flashing (means sending a data uninterruptedly)



12. The program stops at the breakpoint

```
😚 workspace v11 - rfEasyLinkRx CC1352P1 LAUNCHXL tirtos ccs/rfEasyLinkRx.c - Code Composε
File Edit View Project Tools Run Scripts Window Help
E 🔆 8 - -
= rxDoneCb(struct <unnamed> *, int)() at rfEasyLinkRx.c:100 0x00003B8E
ॿ rfEasyLinkRx.c 🛭
  J#11del KILASILINKRX ASYNC
  90 static Semaphore_Handle rxDoneSem;
  91#endif
  93/**** Function definitions *****/
  94#ifdef RFEASYLINKRX_ASYNC
  95 void rxDoneCb(EasyLink_RxPacket * rxPacket, EasyLink_Status status)
  96 {
  97
       if (status == EasyLink_Status_Success)
  98
            /* Toggle RLED to indicate RX */
100
           PIN_setOutputValue(pinHandle, CONFIG_PIN_RLED,!PIN_getOutputValue
101
103
103
       else if(status == EasyLink_Status_Aborted)
            /* Toggle GLED to indicate command aborted */
104
 105
           PIN_setOutputValue(pinHandle, CONFIG_PIN_GLED,!PIN_getOutputValue
 106
       }
107
       else
108
       {
            /* Toggle GLED and RLED to indicate error */
```

BDE-RFM208P-S1 USER



Multi-Band Wireless Module with PA

User Guide

By far you should've built your first application successfully.

For further development, please check out the <u>CC1352P-S1 data sheet, product information and support | Tl.com</u> page and download the User guide <u>(https://www.ti.com/lit/pdf/swcu185)</u>

Other Resources

Mac OS Installer for SimpleLink CC13X2 26X2 SDK

Linux Installer for SimpleLink CC13X2 26X2 SDK

Mac OS Installer for Code Composer Studio IDE

Linux Installer for Code Composer Studio IDE

CC1352P SimpleLink™ High-Performance Multi-Band Wireless MCU With Integrated Power Amplifier

Windows Installer for SmartRF Flash Programmer 2

Revision History

| Revision | Date | Description |
|----------|-------------|------------------|
| V1.0 | 15-Feb-2020 | Initial Released |
| V2.0 | 14-Apr-2021 | Changed template |

More Questions:

Please search existing answers on TI E2E support forums

Contact your local TI sales representative.

Or

Contact BDE Technology, Inc.

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