BDE-RFM208P-2.4 USER GUIDE

Introduction

This user guide is for BDE-RFM208P-2.4, a Wireless Module based on TI CC1352R. It is a quick start guide for how to connect the module with the evaluation board BDE-EVB07 or with the TI launchpad, and how to build the first application. It also shows a demo for how BDE-RFM208P-2.4 receives a data packet that is sent from another BDE-RFM208P-2.4.

Get Ready

The following tools are recommended to develop with BDE-RFM208P-2.4.

Hardware tools:

- Two modules of BDE-RFM208P-2.4(<u>BDE-RFM208P-2.4-BDE Technology Inc.</u> (bdecomm.com))
- Two BDE-ADP208 V1.0 (adaptor board)
- PC or Laptop
- Two BDE-EVB07 (<u>BDE-EVB07-BDE Technology Inc. (bdecomm.com)</u>) or
- Two TI Launchpad (LAUNCHXL-CC13X2R Evaluation board | TI.com)
- USB cable for power supply and debugging

Software tools:

- Terminal software such as CCS, IAR.
- CCS download
- Software Development Kit (SDK)

Build Your First Application

Once have the Hardware and Software tools in place, please following the following steps:

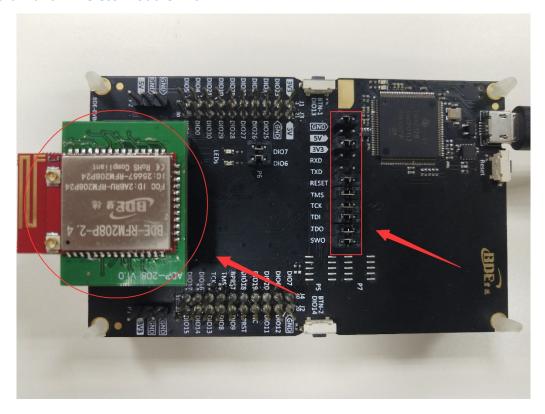
A. Connect the Hardware

If chose EVB07:

Use USB cable to connect EVB07 and PC or laptop. Plug BDE-RFM208P-2.4 with the adaptor board into the dev board and connect all the pins with Jumpers as the following picture shows.

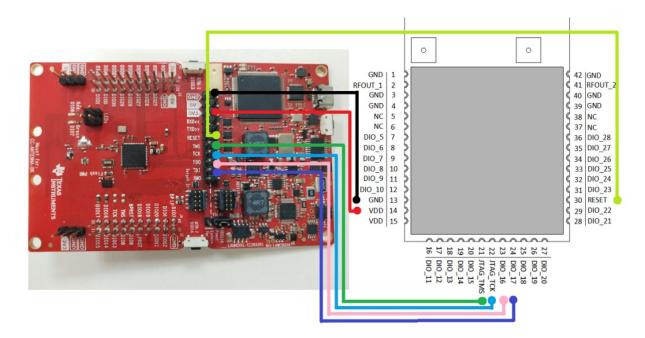


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If chose TI Launchpad:

The connection is as following.



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Connection Designator	BDE-RFM208P-2.4 LaunchPad Pin	
3V3 Power	VDD	3V3
Ground	GND	GND
RST	RST RESET	
TMS	TMS TMS	
TCK	TCK TCK	
TDO	DIO16 TDO	
TDI	DIO17	TDI

Optional: TDO, TDI, RXD, TXD

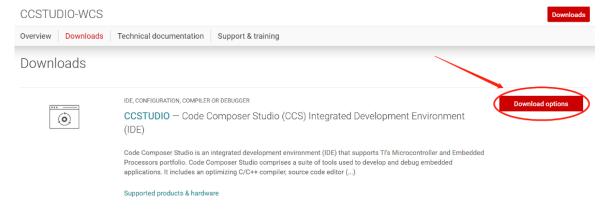
B. Build the Application

Download and install the CCS and SDK

From the above links, follow the instructions in the following steps to download and install the CCS and SDK.

CCS Installation

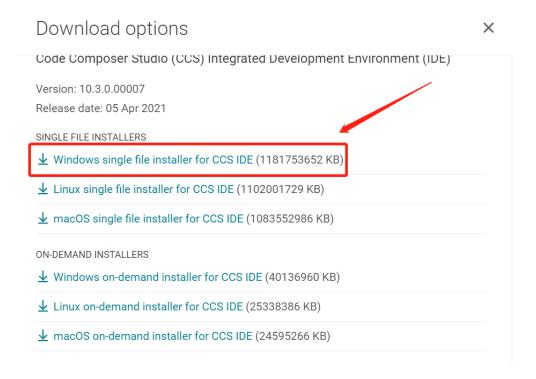
1. Click on this option



2. Select an option to download CCS

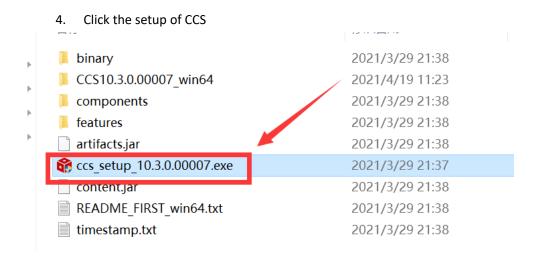


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3. Unzip the package to a local disc

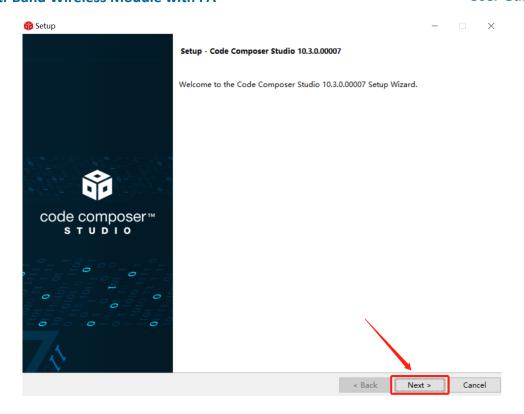




5. Click "Next"



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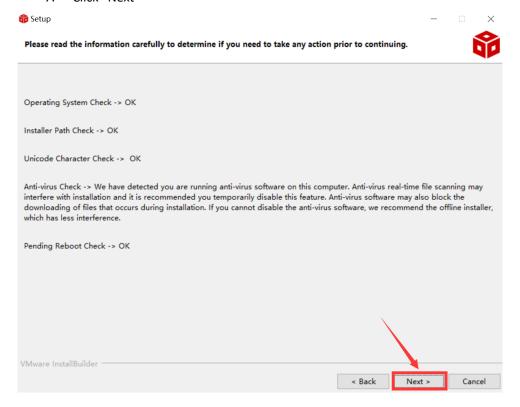
6. Select the default option



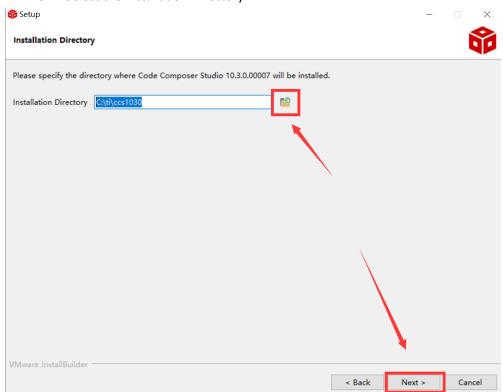


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7. Click "Next"



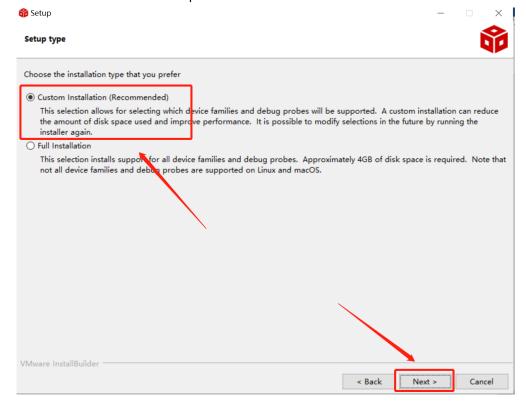
8. Select the Installation Directory



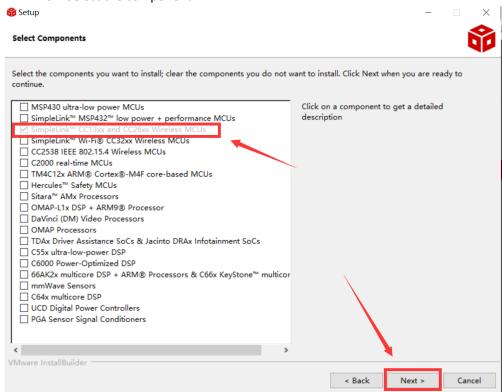


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9. Select the default option



10. Select the component

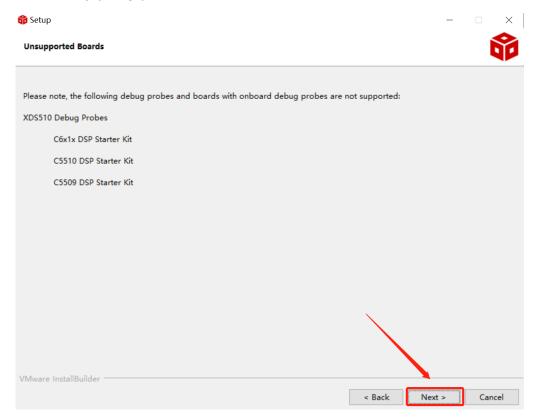




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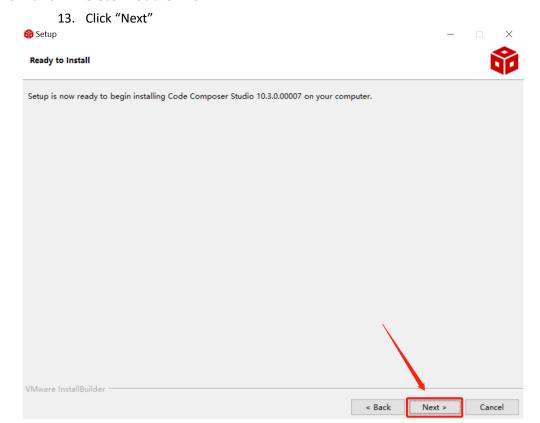


12. Click "Next"

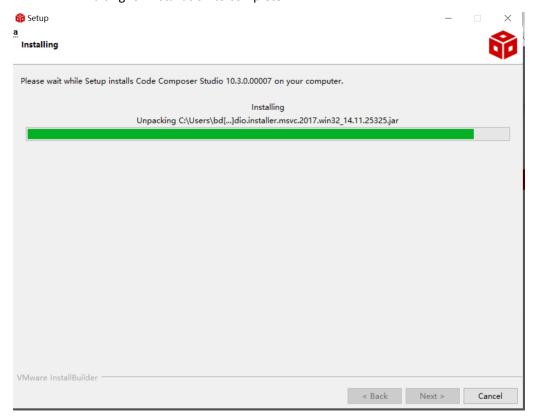




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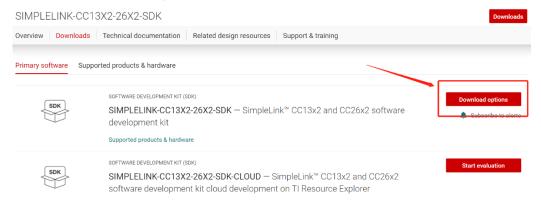
14. Waiting for installation to complete



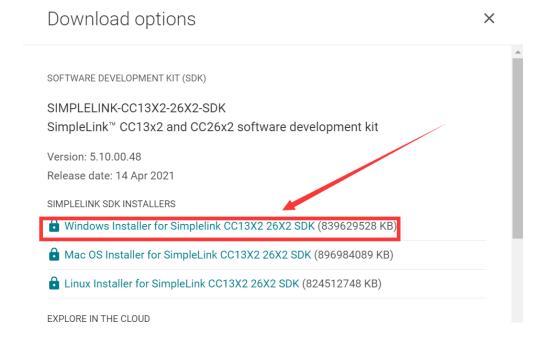


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- Software Development Kit (SDK) installation
 - 1. Click on this option



2. Select an option you need to download SDK



3. Log in to your TI account, if you are a new user, register a TI account first



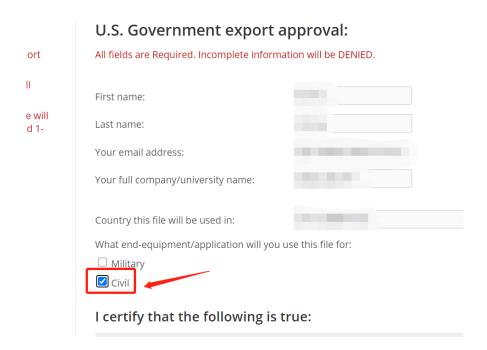
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myTl account

myTI FAQ



4. Select "civil" if your application is for civil use





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5. Select "Yes" and submit

compliance with any such import, use, or export restrictions.

- I / We hereby certify that we will adhere to the conditions above.
- I / We do not know of any additional facts different from the above.
- I / We take responsibility to comply with these terms.
- I / We understand we are responsible to abide by the most current. versions
 of the Export Administration Regulations and other U.S. export and
 sanctions laws.



6. Download SDK

TI Home

TI Request

You have been approved to receive this file. Click "Download" to proceed.

In a few moments, you will also receive an email with the link to this file.

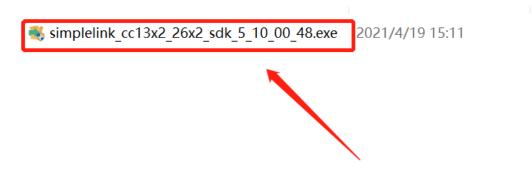


Thank you, Texas Instruments

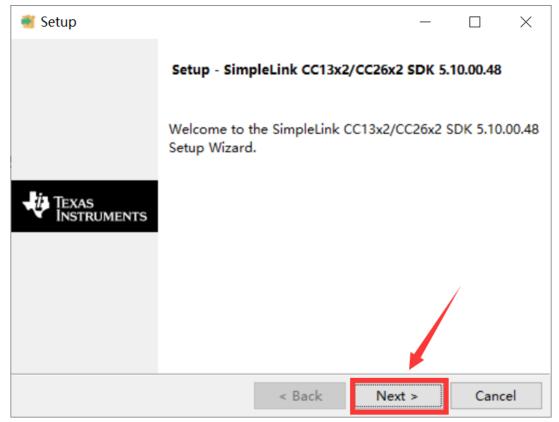
7. Installation



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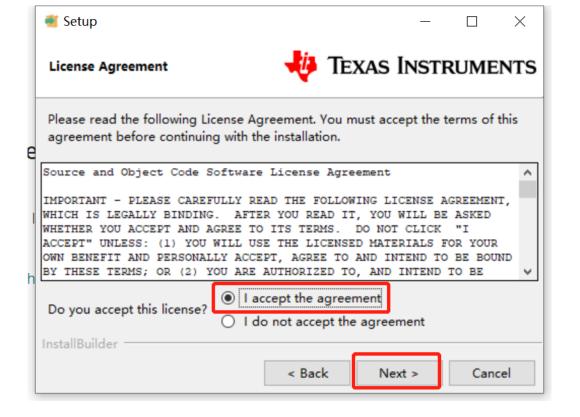
8. Click "Next"



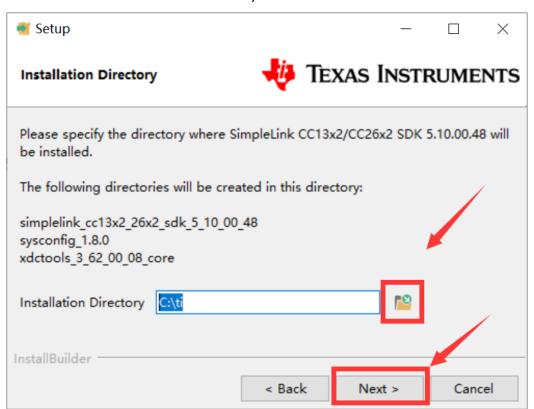
9. Select the default option



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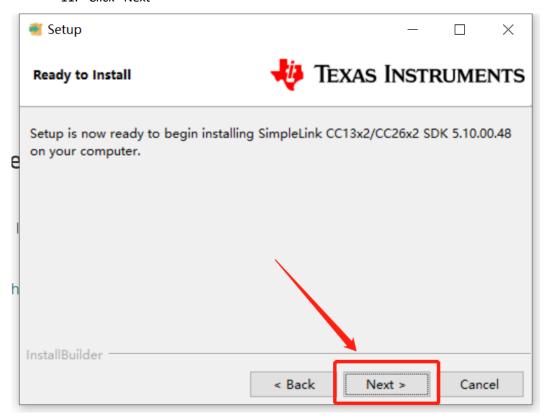
10. Select the Installation directory



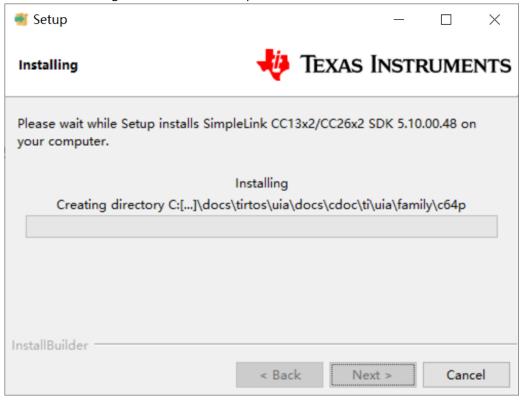


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11. Click "Next"



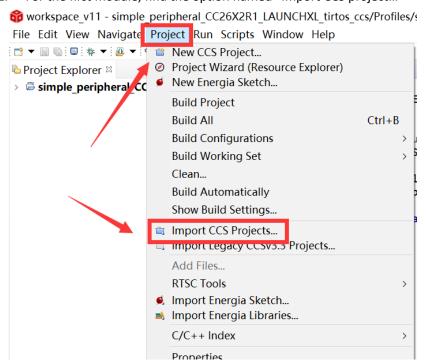
12. Waiting for installation to complete





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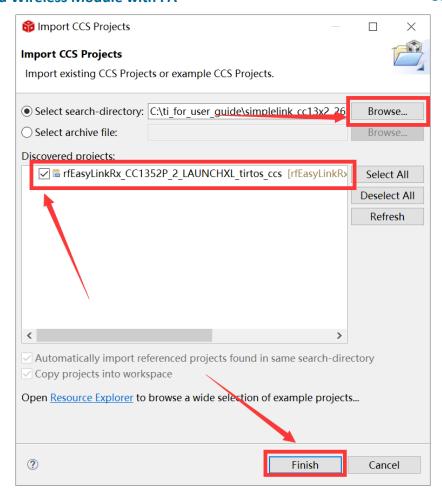
- Run an example/demo code
 - 1. For the first module, find the option named "Import CCS project..."



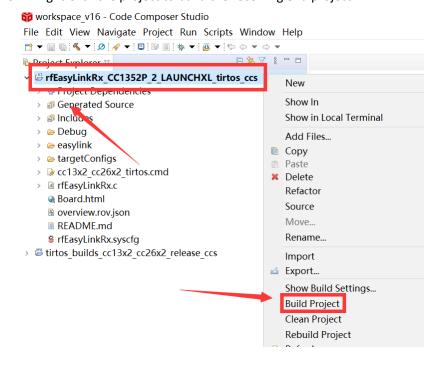
 According to the following path to find the sending end project: ti\simplelink_cc13x2_26x2_sdk_5_10_00_48\examples\rtos\CC1352P_2 _LAUNCHXL\ easylink\ rfEasyLinkRx\tirtos\ccs



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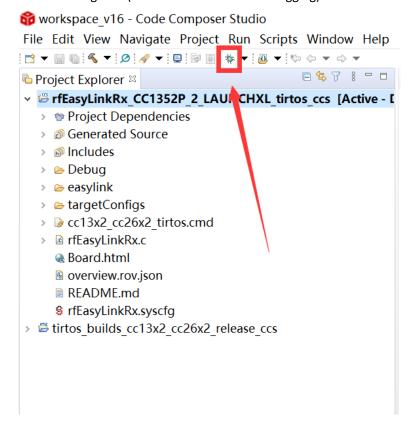
3. Right Click the project to build the receiving end project





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4. Click this bug icon (means download and debugging)



5. Click on this option to start debugging

```
💗 workspace v16 - rfEasyLinkRx CC1352P 2 LAUNCHXL tirtos ccs/rfEasyLinkRx.c - Code C
File Edit View Project Tools Run Scripts Window Help
† Debug ⊠

▼ FEasyLinkRx © 1352P_2 LAUNCHXL_tirtos ccs [Code Composer Studio - Device Debu
  ✓ P Texas Instruments XDS110 USB Debug Probe/Cortex M4 0 (Suspended - HW Break
       = main() at rfEas /LinkRx.c:211 0x000036F0
       c_int00() at boot.asm:254 0x00005068 (_c_int00 does not contain frame inform

☐ rfEasyLinkRx.c 
☐

211 {
         /* Call driver init functions */
 212
 213
        Board_initGeneral();
214
 215
        /* Open LED pins */
        ledPinHandle = PIN open(&ledPinState, pinTable);
 216
 217
        Assert_isTrue(ledPinHandle != NULL, NULL);
 218
 219
        /* Clear LED pins */
 220
        PIN_setOutputValue(ledPinHandle, CONFIG_PIN_GLED, 0);
221
222
        PIN_setOutputValue(ledPinHandle, CONFIG_PIN_RLED, 0);
 223
        rxTask_init(ledPinHandle);
 224
        /* Start BIOS */
 225
 226
        BIOS_start();
```



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6. Find the file which is named "rfEasyLinkRx.c" and the function which is named "rxDoneCb", and set a breakpoint at the line as the arrows shows

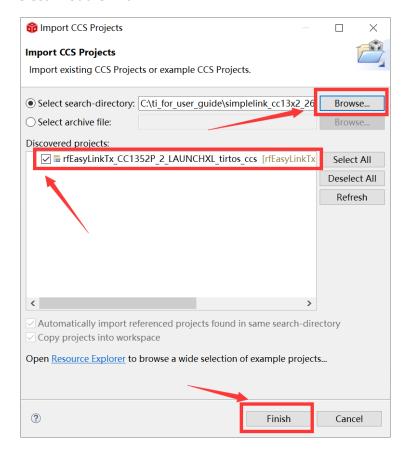
```
😚 workspace v16 - rfEasyLinkRx CC1352P 2 LAUNCHXL tirtos ccs/rfEasyLinkRx.c - Code Comp
File Edit View Project Tools Run Scripts Window Help
v 👽 rfEasyLinkRx CC1352P 2 LAUNCHXL tirtos ccs [Code Composer Studio - Device Debuggin
    Texas Instruments XDS110 USB Debug Probe/Cortex M4 0 (Running)
 rfEasvLinkRx.c ∺
  gostatic Semaphore_Handle rxDoneSem;
  91#endif
  92
  93/**** Function definitions ***
  94#ifdef RFEASYLINKRX ASYNC
  95 void rxDoneCb(EasyLink_RxPacket * rxPacket, EasyLink_Status status)
  96 {
        if (status == EasyLink_Status_Success)
  97
  98
               Toggle RLED to indicate RX */
 100
            PIN_setOutputValue(pinHandle, CONFIG_PIN_RLED,!PIN_getOutputValue)
 101
        else if(status == EasyLink_Status_Aborted)
 10_
 104
            /* Toggle GLED to indicate command aborted */
 105
            PIN_setOutputValue(pinHandle, CONFIG_PIN_GLED,!PIN_getOutputVal
 106
 107
        else
 108
        {
```

7. For another module, according to the following path to find the sending end project:

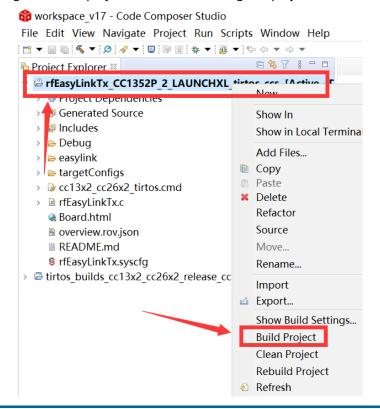
```
ti\simple link_cc13x2_26x2_sdk_5_10_00_48\examples\rtos\cc1352P_2_LAUNCHXL\easy link\rfEasy LinkTx\tirtos\ccs
```



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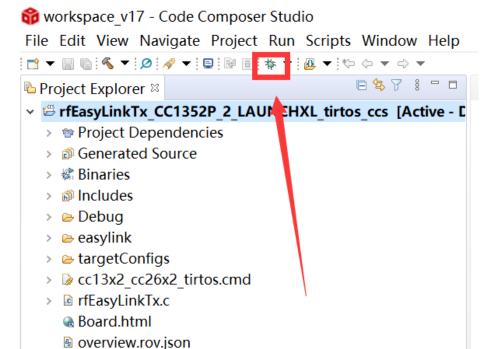
8. Right Click the project to build the sending end project





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9. Click this bug icon (means download and debugging)



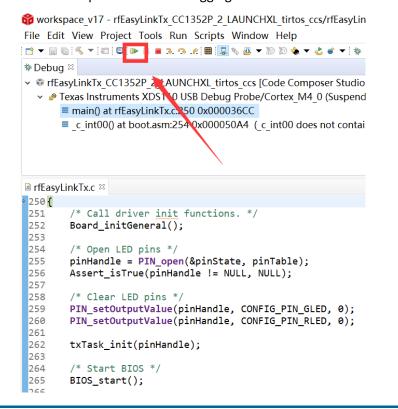
10. Click on this option to start debugging

>

tirtos builds cc13x2 cc26x2 release ccs

README.md

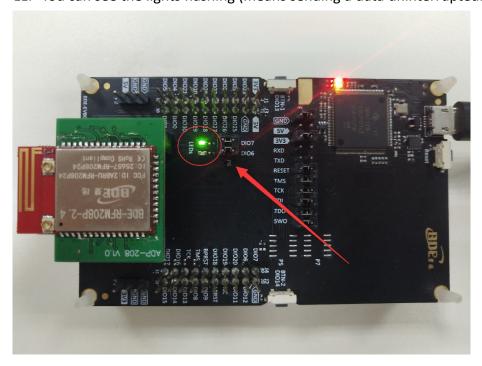
rfEasyLinkTx.syscfg





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11. You can see the lights flashing (means sending a data uninterruptedly)



12. The program stops at the breakpoint

```
😚 workspace_v16 - rfEasyLinkRx_CC1352P_2_LAUNCHXL_tirtos_ccs/rfEasyLinkRx.c - Code Compose
File Edit View Project Tools Run Scripts Window Help
T ▼ 🔊 🖾 ▼ 🔊 🔊 ▼ 🔻 🔻 🔻 🔻 🖟 🖾 ﴿ 🕶 🚇 🖟 🖟 🖟 🖟 🖟 🖟 🖟 🖟 🖟 🖟 🖟 🖟 🖟
v 🕏 rfEasyLinkRx CC1352P 2 LAUNCHXL tirtos ccs [Code Composer Studio - Device Debuggin \wedge

✓ Press Instruments XDS110 USB Debug Probe/Cortex M4 0 (Suspended - HW Breakpoint)

       = rxDoneCb(struct <unnamed> *, int)() at rfEasyLinkRx.c:100 0x00003B8E
🖻 rfEasyLinkRx.c 🛭
  90 static Semaphore_nandle rxDoneSem;
  91#endif
  93/***** Function definitions *****/
  94#ifdef RFEASYLINKRX ASYNC
  95 void rxDoneCb(EasyLink_RxPacket * rxPacket, EasyLink_Status status)
  96 {
  97
         if (status == EasyLink_Status_Success)
  98
         {
             PIN_setOutputValue(pinHandle, CONFIG_PIN_RLED,!PIN_getOutputValue(
2100
         else if(status == EasyLink_Status_Aborted)
 103
 104
             /* Toggle GLED to indicate command aborted */
             PIN_setOutputValue(pinHandle, CONFIG_PIN_GLED,!PIN_getOutputValue(
 105
 106
 107
 108
 109
               Toggle GLED and RLED to indicate error */
■ Console 🛛
rfEasyLinkRx CC1352P 2 LAUNCHXL tirtos ccs
Cortex M4 0: GEL Output: Memory Map Initialization Complete.
```

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By far you should've built your first application successfully.

For further development, please check out the CC1352P-2.4 data sheet, product information and support | Tl.com page and download the User guide (https://www.ti.com/lit/pdf/swcu185)

Other Resources

Mac OS Installer for SimpleLink CC13X2 26X2 SDK

Linux Installer for SimpleLink CC13X2 26X2 SDK

Mac OS Installer for Code Composer Studio IDE

Linux Installer for Code Composer Studio IDE

CC1352P SimpleLink™ High-Performance Multi-Band Wireless MCU With Integrated Power Amplifier

Windows Installer for SmartRF Flash Programmer 2

Revision History

Revision	Date	Description
V1.0	15-Feb-2020	Initial Released
V2.0	14-Apr-2021	Changed template

More Questions:

Please search existing answers on TI E2E support forums

Contact your local TI sales representative.

Or

Contact BDE Technology, Inc.

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Website: http://www.bdecomm.com/cn/ Email: shu@bdecomm.com

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Website: http://www.bdecomm.com/ Email: info@bdecomm.com/